

VIETNAM NATIONAL UNIVERSITY, HANOI  
 University of Engineering and Technology

Date: June 14, 2015

**FINAL EXAMINATION**  
 Course: **Signals and Systems (ELT2035)**  
 Duration: 90 minutes

**Part 1 (Multiple-choice questions):** For problems in this part, you only have to give the letter of the correct answer (A/B/C/D). Explanations are not required.

**Problem 1.** Which one of the LTI systems represented by the following impulse responses is stable?

- A.  $h(t) = \sin(3\pi t)u(t)$
- B.  $h(n) = \cos(\pi n/3)[u(n+5) - u(n-5)]$
- C.  $h(n) = u(-n)$
- D.  $h(t) = (e^{2t} - e^{-2t})u(t)$

**Problem 2.** What is the Nyquist rate of the signal

$$x(t) = \cos(800\pi t + \pi/2) + 2\sin(1600\pi t + \pi/4) + 3$$

- A. 400 Hz
- B. 800 Hz
- C. 1600 Hz
- D. 3200 Hz

**Problem 3.** Given a discrete-time LTI system described by the difference equation  $4y(n) + y(n-2) = x(n-1)$ , which one of the following statements about this system is correct?

- A. The system is stable if it is causal.
- B. The system is stable if it is anti-causal.
- C. The system is stable if it is non-causal.
- D. The system is unstable.

**Problem 4.** A discrete-time signal  $x(n]$  has the Fourier transform given by

$$X(\Omega) = \frac{4e^{j\Omega} - 5}{2e^{j2\Omega} - 5e^{j\Omega} + 2}. \text{ What is } x(n)?$$

- A.  $2^{-n}u(n) + 2^n u(n)$

**B.**  $-2^{-n}u(-n-1)-2^n u(-n-1)$

**C.**  $2^{-n}u(n)-2^n u(-n-1)$

**D.**  $-2^{-n}u(-n-1)+2^n u(n)$

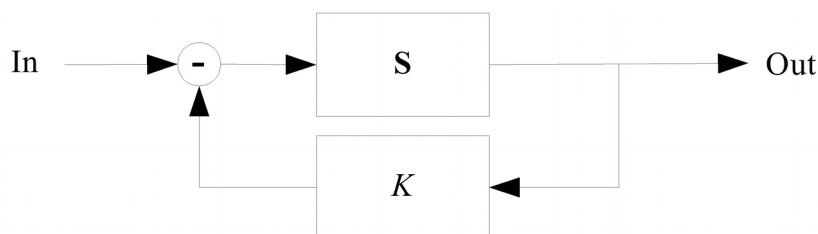
**Part 2 (Exercises):** For problems in this part, detailed explanations/derivations that lead to the answers must be provided.

**Problem 5.** Given a causal LTI system described by the following difference equation:

$$2y(n)+3y(n-1)+y(n-2)=2x(n-1)$$

- Determine the impulse response of the given system.
- Determine the zero-state response  $y_s(n)$  of the given system to the step input  $x(n)=u(n)$ .

**Problem 6.** Given a causal system **T** described by the following block diagram:



in which, **S** is a continuous-time LTI system described by the differential equation  $y(t)-\frac{dy(t)}{dt}=x(t)+\frac{dx(t)}{dt}$  and  $K$  is a constant.

- Determine the condition for  $K$  so that system **T** is stable.
- Determine the frequency response and the magnitude response of system **T** when  $K = 2$ .
- Determine the output signal  $y(t)$  of system **T** when  $K = 2$  and the input signal  $x(t)=\cos(3\pi t+\pi/4)+2\sin(\pi t/2)+1$ .
- Compute the power of the output signal  $y(t)$  obtained in c).

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