

**FINAL EXAM – SEMESTER II, 2019-2020**  
CONTROL ENGINEERING - ELT 3051 26. Duration: 90 minutes

*The exam includes one page. Students are not allowed to use any documents*

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Q1: The differential equation of system is shown as follow

$$\frac{d^2y(t)}{dt^2} + 4,2\frac{dy(t)}{dt} + 36y(t) = 36x(t)$$

- Find the transfer function of system
- Write an expression for the general form of the step response without solving for the inverse Laplace transform. State the nature of response.
- Determine the settling time, peak time and percent overshoot of the second order system.

Q2: A unity feedback system has the following forward transfer function:

$$G(s) = \frac{10(s + 10)(s + 20)}{s(s + 15)(s + 25)}$$

- Find the steady state error for the following inputs:  $u(t)$ ,  $tu(t)$ ,  $t^2u(t)$
- Determine the stability of the feedback system?

Q3: Given a unity feedback system that has the forward path transfer function

$$G(s) = \frac{K}{(s + 2)(s + 4)(s + 6)}$$

- Sketch the root locus and find the range of  $K$  for stable system.
- The Nyquist diagram of the open loop system with  $K = 100$  is shown in the Figure 1.
  - Using the Nyquist criterion, find out whether the closed loop system is stable or not?
  - Determine the gain and phase margin of closed loop system?

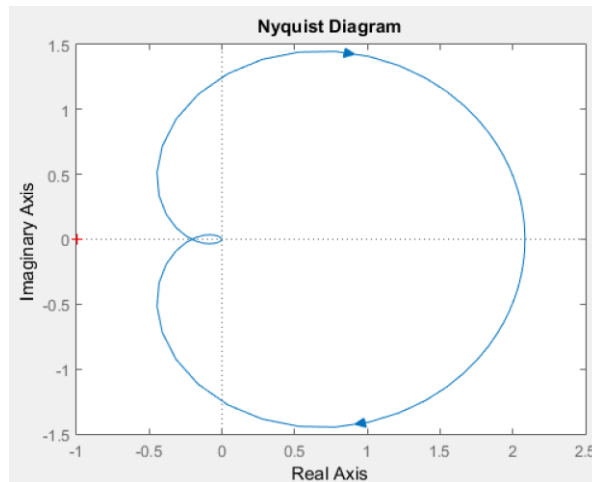


Figure 1

**SOLUTION FINAL EXAM – SEMESTER II, 2019-2020**  
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**Q1 (3 marks):**

a.  $36/s^2 + 4.2s + 36$

b.  $s_{1,2} = -2.1 \pm j 5.6$

$y(t) = 1 * A \exp(-2.1t) * \cos(5.6t + \phi)$

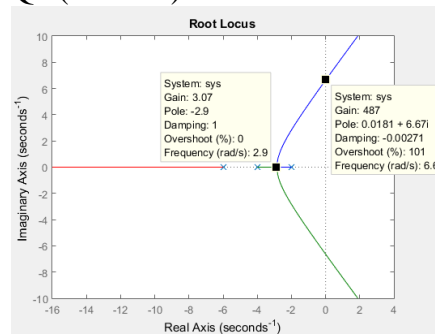
c.  $T_p = 1.31$ ,  $OS = 30.9\%$ ,  $T_s = 1.89$  s

**Q2 (2 marks)**

a.  $e(\text{step})=0$ ,  $e(\text{ramp})=\text{constant}$ ,  $e(\text{parabol})=\text{infinite}$

b. The closed loop system is unstable

**Q3 (5 marks)**



- The system is stable
- $GM = 13.6$  (db)  $w_c = 6.63$  rad/s.  $PM = 72.7$   $w_p = 2.54$